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A Thesis Submitted

in Partial Fulfilment of the Requirements

for the Degree of

DOCTOR OF PHILOSOPHY

by

Name of the Student

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DEPARTMENT OF XYZ INDIAN INSTITUTE OF TECHNOLOGY ROPAR

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Journal

Article 1

Article 2

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Article 1

Article 2

Book chapter

Chapter 1

Patent

Patent 1

The list of publication may also be placed at the end of the thesis, after Appendix as per student/supervisor wish

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List of Symbols

- μ dynamic viscosity, Pa-s
- ρ density, kg/m³

xviii List of Symbols

Chapter 1

Introduction

You can decide your own number of chapters and chapter names, based on your work.

1.1 Introduction

Chapter 2

Literature Review

2.1 Literature

This is an example of citing a reference: Prasad and Goyal [1] developed a strain based computational model which predicts the new bone sites on the periosteal surface.

You can also cite as follows [2].

For more information about referencing citation, you can go through this document.

2.1.1 In-line mathematics

You can write mathematics in a line by using \((and \), e.g., $\sigma = E\varepsilon$

2.1.2 Equation without numbering

$$\rho \frac{D\vec{V}}{Dt} = -\nabla p + \rho \vec{g} + \mu \nabla^2 \vec{V}$$

2.1.3 Equations with numbering

Here a newcommand '\pde' is used to write partial differential equation. The command has been defined in *packages.tex* file. You can cross-refer an equation as follows: Equation 2.1 is the Laplace's equation.

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \tag{2.1}$$

$$\begin{bmatrix} \sigma_{1} \\ \sigma_{2} \\ \sigma_{3} \\ \sigma_{4} \\ \sigma_{5} \\ \sigma_{6} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & C_{14} & C_{15} & C_{16} \\ & C_{22} & C_{23} & C_{24} & C_{25} & C_{26} \\ & & C_{33} & C_{34} & C_{35} & C_{36} \\ & & & C_{44} & C_{45} & C_{46} \\ & & & & & C_{55} & C_{56} \\ & & & & & & C_{66} \end{bmatrix} \begin{bmatrix} \varepsilon_{1} \\ \varepsilon_{2} \\ \varepsilon_{3} \\ \varepsilon_{4} \\ \varepsilon_{5} \\ \varepsilon_{6} \end{bmatrix}$$

$$(2.2)$$

2.1.4 Equations array

$$\frac{\partial}{\partial t} \left(\rho A \frac{\partial u}{\partial t} \right) - \frac{\partial}{\partial x} \left(E A \frac{\partial u}{\partial t} \right) - f = 0, \quad 0 < x < L$$
 (2.3)

$$\left(EA\frac{\partial u}{\partial x}\right)\Big|_{x=L} - P = 0$$
(2.4)

2.1.5 Using bold font with math mode

Here, ∇ and σ are in bold font.

$$\int_{\Omega} \tilde{w}(\boldsymbol{\nabla}_{s}^{T} \tilde{\boldsymbol{\sigma}}) d\Omega = 0 \quad \forall w$$

2.1.6 Align equations

You can use '&' for aligning equation about a symbol as follows:

$$(\log N_f)^{-1/2} = 1.20551064 + 0.66002143 \text{ S} + 0.18040042S^2 - 0.00814329 \text{ S}^4 + 0.00025308\text{RS}^4$$
$$+ 0.00021832\text{TS}^4 - 0.00054660\text{RT}^2 - 0.005567\text{RH}^2 - 0.00293919\text{HR}^2$$
$$+ 0.0119714\text{HT} - 0.00051639\text{H}^2 \text{ T}^2$$

$$V = \iiint \rho^2 \sin\theta d\rho d\theta d\varphi$$

$$= \int_0^{2\pi} \int_0^{\pi} \int_0^r \rho^2 \sin\theta d\rho d\theta d\varphi$$

$$= 2\pi \int_0^{\pi} \int_0^r \rho^2 \sin\theta d\rho d\theta$$

$$= 4\pi \int_0^r \rho^2 d\rho$$

$$= \frac{4\pi}{3} \rho^3$$

Chapter 3

Methodology

3.1 Adding a table

Table 3.1 shows the compositions of the materials used in the study.

Table 3.1: The chemical composition of base metal and weld metal by wt. (%)

Material	C	Mn	\mathbf{Si}	\mathbf{Cr}	Ni	Mo	N	S	P	Fe
DSS 2205	0.02	0.84	0.41	22.84	4.65	3.80	0.186	0.003	0.028	Bal.
ER 2209	0.01	1.80	0.40	22.70	8.50	3.20	0.160	0.001	0.015	Bal.

3.2 Adding a figure

You can use vector files (.eps, .pdf) or image files (.jpeg, .png) to insert a figure (see Figure 3.1). One can use Ipe drawing editor or LaTexDraw to make schematics figures in vector format.

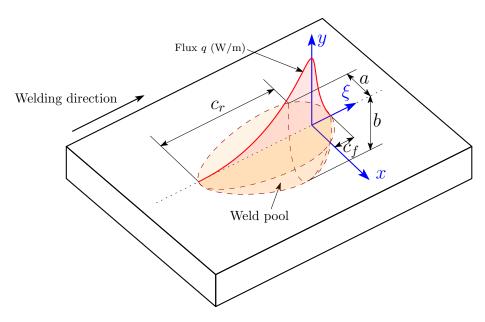


Figure 3.1: A schematic

3.3 Adding sub-figures

This is an example of cross-referring figures. Figure 3.2a shows the slip plane in a FCC system.

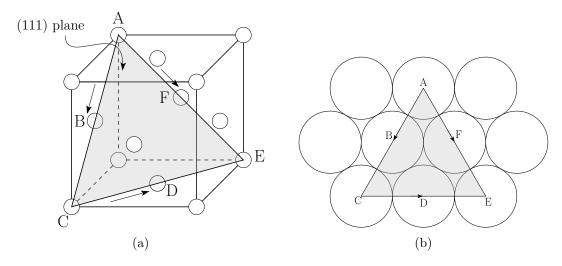


Figure 3.2: An schematic representation of (a) face centred cubic slip system, (b) (110) plane

Chapter 4

Results and Discussion

4.1 Results

Chapter 5

Conclusion

5.1 Conclusion

References

- [1] Jitendra Prasad and Ajay Goyal. An invertible mathematical model of cortical bone's adaptation to mechanical loading. *Scientific reports*, 9(1):1–14, 2019.
- [2] Celine Cabet, Laura Carroll, and Richard Wright. Low cycle fatigue and creep-fatigue behavior of alloy 617 at high temperature. *Journal of Pressure Vessel Technology*, 135 (6), 2013.

12 References

Chapter A

Appendix Title